

# **Automatic Complexity Analysis of Integer Programs via Triangular Weakly Non-Linear Loops**

# **11th International Joint Conference on Automated Reasoning**

Nils Lommen, Eleanore Meyer, and Jürgen Giesl

$$
\begin{array}{c} \text{while } (x_1^2 < x_2 \land x_1 > 0) \text{ do} \\ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \leftarrow \begin{bmatrix} 2 \cdot x_1 + x_3^2 \\ 3 \cdot x_2 \\ x_3 \end{bmatrix} \\ \text{end} \\ \\ \text{end} \end{array}
$$

**Goal**: Infer (upper) runtime bounds for "real-world" programs

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\begin{array}{c} \text{while } (x_1^2 < x_2 \land x_1 > 0) \text{ do} \\ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \leftarrow \begin{bmatrix} 2 \cdot x_1 + x_3^2 \\ 3 \cdot x_2 \\ x_3 \end{bmatrix} \\ \text{end} \\ \\ \text{end} \end{array}
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▶ Does this loop terminate?

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\begin{array}{c}\text{while } (x_1^2 < x_2 \land x_1 > 0) \text{ do} \\ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \leftarrow \begin{bmatrix} 2 \cdot x_1 + x_3^2 \\ 3 \cdot x_2 \\ x_3 \end{bmatrix} \\ \text{end} \\ \\
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- ▶ Does this loop terminate?
- ▶ How often do we execute the loop?

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\begin{array}{c} \text{while } (x_1^2 < x_2 \land x_1 > 0) \text{ do} \\ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \leftarrow \begin{bmatrix} 2 \cdot x_1 + x_3^2 \\ 3 \cdot x_2 \\ x_3 \end{bmatrix} \\ \text{end} \end{array}
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- ▶ Does this loop terminate?
- ▶ How often do we execute the loop?
	- Linear ranking functions fail.

 $\overline{1}$ 

end

x2

while 
$$
(x_1^2 < x_2 \land x_1 > 0)
$$
 do  
\n $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \begin{bmatrix} 2 \cdot x_1 + x_2^2 \\ x_2 \end{bmatrix}$ 

$$
\begin{array}{c}\n\mathtt{x}_1 \\
\mathtt{x}_2 \\
\mathtt{x}_3\n\end{array}\n\leftarrow\n\begin{bmatrix}\n2 \cdot \mathtt{x}_1 + \mathtt{x}_3^2 \\
3 \cdot \mathtt{x}_2 \\
\mathtt{x}_3\n\end{bmatrix}
$$

- ▶ Does this loop terminate?
- ▶ How often do we execute the loop?
	- Linear ranking functions fail.
	- Existing tools usually fail with non-linear arithmetic

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\begin{array}{ll}\n\text{while } (x_1^2 < x_2 \land x_1 > 0) \text{ do} \\
\text{[x,]} & [2 \cdot x_1 + x_2^2]\n\end{array}
$$

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\begin{bmatrix} \mathtt{x}_1 \\ \mathtt{x}_2 \\ \mathtt{x}_3 \end{bmatrix} \leftarrow \begin{bmatrix} 2\cdot\mathtt{x}_1 + \mathtt{x}_3^2 \\ 3\cdot\mathtt{x}_2 \\ \mathtt{x}_3 \end{bmatrix}
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end

- ▶ Does this loop terminate?
- ▶ How often do we execute the loop?
	- Linear ranking functions fail.
	- Existing tools usually fail with non-linear arithmetic
	- Can compute non-linear runtime bounds for twn-loops.

 $X_3$ 

end

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▶ Combine [TOPLAS '16] and [SAS '20; LPAR '20] in automatic complexity analysis tool KoAT

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- ▶ Does this loop terminate?
- ▶ How often do we execute the loop?
	- Linear ranking functions fail.
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	- Can compute non-linear runtime bounds for twn-loops.
- ▶ Combine [TOPLAS '16] and [SAS '20; LPAR '20] in automatic complexity analysis tool KoAT
- $\blacktriangleright$  Approach is complete for all terminating twn-loops



3 of 16 IJCAR 2022 **Nils Lommen**, Eleanore Meyer, and Jürgen Giesl RWTH Aachen University – LuFGi2













# **TWN-Loops**

while (7) do  
\n
$$
\begin{bmatrix} x_1 \\ \cdots \\ x_d \end{bmatrix} \leftarrow \begin{bmatrix} c_1 \cdot x_1 + p_1 \\ \cdots \\ c_d \cdot x_d + p_d \end{bmatrix}
$$
\nend

▶ *τ* built from *∧*, *∨*, (*¬*, …) and polynomial inequations over  $\mathbb Z$ 

# **TWN-Loops**

while 
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(\tau)
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 do  
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\blacktriangleright c_1,\ldots,c_d\in\mathbb{Z}
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▶ Variable value depends at most linearly on its previous value.

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- ▶ *τ* built from *∧*, *∨*, (*¬*, …) and polynomial inequations over  $\mathbb Z$
- ▶  $c_1, \ldots, c_d \in \mathbb{Z}$

- ▶ Variable value depends at most linearly on its previous value.
	- Prevent super-exponential growth:  $x \leftarrow x^2$  (so the value is  $2^{(2^i)} \cdot e$ )

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\blacktriangleright p_i \in \mathbb{Z}[x_{i+1},\ldots,x_d] \text{ non-linear}
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	- No cyclic dependencies:  $x_1 \leftarrow x_2$  and  $x_2 \leftarrow x_1$



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 $\blacktriangleright$  Closed forms after *i* iterations w.r.t. initial values  $e_1, e_2$  and  $e_3$ :

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• Value of  $x_1$ :  $2^i \cdot (e_1 + e_3^2)$  $\binom{2}{3}$  –  $e_3^2$ 3

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• Value of  $x_1^2$ 2:  $(2^i \cdot (e_1 + e_3^2))$  $\binom{2}{3}$  –  $e_3^2$  $_{3}^{2})^{2}$ 

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 Value of  $x_3^2$  always non-negative

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► Value of 
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\n• Removing  $x_3^2$  increases runtime

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\begin{array}{l} \text { while } \left(x_1^2 < x_2 \wedge x_1 > 0 \right) \text { do } \\ \left[x_1\atop x_2\right] \leftarrow \left[2 \cdot x_1\atop 3 \cdot x_2\right] \\ \text { end } \end{array}
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• Value of  $x_1^2$  $\frac{2}{1}$ :  $(2^i \cdot e_1)^2 = 4^i \cdot e_1^2$ 1

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- $\blacktriangleright$  Value of  $x_3^2$  always non-negative • Removing  $x_3^2$  $\frac{2}{3}$  increases runtime
- $\blacktriangleright$  Eliminated non-linear occurrence of  $x_3$ in closed forms

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- ▶ Novel approach infers tighter bounds than [LPAR '20]

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- Value of  $x_2$ :  $3^i \cdot e_2$
- ▶ KoAT automatically infers closed forms [CAV '19] and applies simplification

#### **Overview**



#### Does the loop terminate?

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▶ Yes!

▶ Value of  $\frac{x_1^2}{x_1}$  eventually *outgrows* value of  $x_2$ 

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- ▶ Yes!
- ▶ Value of  $\frac{x_1^2}{x_1}$  eventually *outgrows* value of  $x_2$
- ▶ At some point we always have

$$
4^i \cdot e_1^2 \ge 3^i \cdot e_2.
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#### $\blacktriangleright$  Reduce Termination to an existential formula over  $\mathbb Z$  [SAS '20]

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	- linear arithmetic: co-NP-complete

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- $\blacktriangleright$  Reduce Termination to an existential formula over  $\mathbb Z$  [SAS '20]
	- linear arithmetic: co-NP-complete
	- $\cdot$  non-linear arithmetic: non-termination is semi-decidable

#### **Overview**



**Goal**: Infer (upper) runtime bounds for "real-world" programs

$$
\begin{array}{ll}\text{while } (x_1^2 < x_2 \land x_1 > 0) \text{ do} \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \leftarrow \begin{bmatrix} 2 \cdot x_1 \\ 3 \cdot x_2 \end{bmatrix} \\ \text{end} \end{array}
$$

Closed forms w.r.t. initial values  $e_1$  and  $e_2$ :

► Value of 
$$
x_1^2
$$
:  $(2^i \cdot e_1)^2 = 4^i \cdot e_1^2$  \n► Value of  $x_2$ :  $3^i \cdot e_2$ 

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 $4^{i} \cdot e_1^2 < 3^{i} \cdot e_2$ 

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 $4^i \cdot e_1^2 - 3^i \cdot e_2 < 0$ 

▶ When does the sign of  $4^{i} \cdot e_1^2 - 3^{i} \cdot e_2$  only depend on  $e_1^2$ ?

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- ▶ When does the sign of  $4^{i} \cdot e_1^2 3^{i} \cdot e_2$  only depend on  $e_1^2$ ?
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- ▶ At this point, the loop terminates or never will.
- ▶ Bound on stabilization threshold can be computed *automatically*
- ▶ Improve [LPAR '20] by considering variables individually

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▶ Bound the point where the truth value of the guard stabilizes.

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 $4^{i} > -3^{i} \cdot e_{2}$ 

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**Goal**: Infer (upper) runtime bounds for "real-world" programs

$$
\begin{array}{l} \text { while } \left(x_1^2 < x_2 \wedge x_1 > 0 \right) \text { do } \\ \left[x_1\atop x_2\right] \leftarrow \left[2 \cdot x_1\atop 3 \cdot x_2\right] \\ \text { end } \end{array}
$$

▶ When do we have  $4^i > -3^i \cdot e_2$ ? ▶ Prove:  $i > |e_2|$  implies  $4^i > -3^i \cdot e_2$ 



▶ Bound the point where the truth

value of the guard stabilizes.

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$$

▶ Bound the point where the truth value of the guard stabilizes.

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▶ Bound the point where the truth value of the guard stabilizes.

- ▶ When do we have  $4^i > -3^i \cdot e_2$ ?
- ▶ Prove:  $i > |e_2|$  implies  $4^i > -3^i \cdot e_2$
- $\blacktriangleright$  By Termination:  $|e_2| + 1$  is runtime bound
- ▶ Procedure is complete and implemented in *KoAT*

 $4^{i} > -3^{i} \cdot e_{2}$  $(4/3)^i > -e_2$  $(4/3)^i > |e_2|$  $i > log(|e_2|)$ 

#### **Overview**



**Goal**: Infer (upper) runtime bounds for "real-world" programs

$$
\begin{array}{c} \text{while } (x_1^2 < x_2) \text{ do} \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \leftarrow \begin{bmatrix} 2 \cdot x_1 \\ 3 \cdot x_2 \end{bmatrix} \end{array}
$$

end

$$
\begin{array}{l} \text{while } (x_3 > 0) \text{ do} \\ \\ \text{while } (x_1^2 < x_2) \text{ do} \\ \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \leftarrow \begin{bmatrix} 2 \cdot x_1 \\ 3 \cdot x_2 \end{bmatrix} \\ \\ \text{end} \end{array}
$$

$$
\begin{aligned}\n\text{while } (x_3 > 0) \text{ do} \\
\text{while } (x_1^2 < x_2) \text{ do} \\
\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} < \begin{bmatrix} 2 \cdot x_1 \\ 3 \cdot x_2 \end{bmatrix} \\
\text{end} \\
\begin{bmatrix} x_3 \end{bmatrix} < \begin{bmatrix} x_3 - 1 \end{bmatrix}\n\end{aligned}
$$

$$
\begin{array}{l} \text{while } (x_3 > 0) \text{ do} \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \leftarrow \begin{bmatrix} x_4 \\ x_2^2 \end{bmatrix} \\ \text{while } (x_1^2 < x_2) \text{ do} \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \leftarrow \begin{bmatrix} 2 \cdot x_1 \\ 3 \cdot x_2 \end{bmatrix} \\ \text{end} \\ \begin{bmatrix} x_3 \end{bmatrix} \leftarrow \begin{bmatrix} x_3 - 1 \end{bmatrix} \\ \text{end} \end{array}
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\begin{array}{l} \text { while } \left( x_3 > 0 \right) \text { do } \\ \left[ \begin{matrix} x_1 \\ x_2 \end{matrix} \right] \leftarrow \left[ \begin{matrix} x_4 \\ x_2^2 \end{matrix} \right] \\ \text { while } \left( x_1^2 < x_2 \right) \text { do } \\ \left[ \begin{matrix} x_1 \\ x_2 \end{matrix} \right] \leftarrow \left[ \begin{matrix} 2 \cdot x_1 \\ 3 \cdot x_2 \end{matrix} \right] \\ \text { end } \\ \left[ \begin{matrix} x_3 \end{matrix} \right] \leftarrow \left[ \begin{matrix} x_3 - 1 \end{matrix} \right] \\ \text { end } \end{array}
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\begin{array}{l} \text { while } \left(x_3>0\right) \text { do } \\ \left[x_1\atop{x_2}\right] \leftarrow \left[\begin{matrix} x_4 \\ x_2^2 \end{matrix}\right] \\ \text { while } \left(x_1^2 < x_2\right) \text { do } \\ \left[\begin{matrix} x_1 \\ x_2 \end{matrix}\right] \leftarrow \left[\begin{matrix} 2 \cdot x_1 \\ 3 \cdot x_2 \end{matrix}\right] \\ \text { end } \\ \left[\begin{matrix} x_3 \end{matrix}\right] \leftarrow \left[\begin{matrix} x_3-1 \end{matrix}\right] \\ \text { end } \end{array}
$$

▶ How often do we execute the inner loop?

**Goal:** Infer (upper) runtime bounds for "real-world" programs

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\begin{array}{l} \text{while } (x_3 > 0) \text{ do} \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \leftarrow \begin{bmatrix} x_4 \\ x_2^2 \end{bmatrix} \\ \text{while } (x_1^2 < x_2) \text{ do} \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \leftarrow \begin{bmatrix} 2 \cdot x_1 \\ 3 \cdot x_2 \end{bmatrix} \\ \text{end} \\ \begin{bmatrix} x_3 \end{bmatrix} \leftarrow \begin{bmatrix} x_3 - 1 \end{bmatrix} \\ \text{end} \end{array}
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- ▶ How often do we execute the inner loop?
- ▶ Idea: Analyze different subprograms and combine results

**Goal:** Infer (upper) runtime bounds for "real-world" programs

$$
\begin{aligned}\n\text{while } (x_3 > 0) \text{ do} \\
\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} < \begin{bmatrix} x_4 \\ x_2^2 \end{bmatrix} \\
\text{costs: } |e_2| + 1 \\
\begin{bmatrix} x_3 \end{bmatrix} < \begin{bmatrix} x_3 - 1 \end{bmatrix} \\
\text{end}\n\end{aligned}
$$

- ▶ How often do we execute the inner loop?
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Inner loop executions:  $(|e_2|+1)$ 

**Goal:** Infer (upper) runtime bounds for "real-world" programs

while  $(x_3 > 0)$  do  $\sqrt{x_1}$  $\mathbf{x}_2$ ] *←*  $\sqrt{X_4}$  $x_5^2$ 5 ]  $\csc |e_2| + 1$  $\left[$ x<sub>3</sub> $\right]$ *←*  $\left[x_3-1\right]$ end

- ▶ How often do we execute the inner loop?
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- ▶ Respect size of variables:

Inner loop executions:  $(|e_2|+1)$ 

**Goal**: Infer (upper) runtime bounds for "real-world" programs

while  $(x_3 > 0)$  do costs:  $|e_5^2$  $|\frac{2}{5}|+1$  $\left[$ x<sub>3</sub> $\right]$ *←*  $\left[x_3-1\right]$ end

- ▶ How often do we execute the inner loop?
- ▶ Idea: Analyze different subprograms and combine results
- $\blacktriangleright$  Respect size of variables:
	- $\bullet$  Size of  $x_2$  is bounded by  $e_5^2$  before inner loop

#### Inner loop executions:  $(|e_5|^2 + 1)$

13 of 16 IJCAR 2022 **Nils Lommen**, Eleanore Meyer, and Jürgen Giesl RWTH Aachen University – LuFGi2

**Goal**: Infer (upper) runtime bounds for "real-world" programs

while  $(x_3 > 0)$  do costs:  $|e_5^2$  $\frac{2}{5}$ | + 1  $\left[ x_{3}\right]$ *←*  $\left[ x_{3}-1\right]$ end

- ▶ How often do we execute the inner loop?
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- ▶ Respect size of variables:
	- $\bullet$  Size of  $x_2$  is bounded by  $e_5^2$  before inner loop
- $\blacktriangleright$  Use ranking functions (M $\Phi$ RFs) to analyze outer loop

Inner loop executions:  $|e_3| \cdot (|e_5|^2 + 1)$ 

**Goal**: Infer (upper) runtime bounds for "real-world" programs

```
while (x_3 > 0) do
    costs: |e_5^2\frac{2}{5}| + 1
    \left[x<sub>3</sub>\right]←
                   \left[x_3-1\right]end
```
- ▶ How often do we execute the inner loop?
- ▶ Idea: Analyze different subprograms and combine results
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Inner loop executions:  $|e_3| \cdot (|e_5|^2 + 1) \in \mathcal{O}(n^3)$ 

#### **Overview**



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▶ C\_Complexity consisting of 504 (mainly linear) benchmarks from TPDB



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#### $\mathcal{O}(1)$   $\mathcal{O}(n)$   $\mathcal{O}(n^2)$   $\mathcal{O}(n^{>2})$ ) *< ∞* AVG(s)

▶ C\_Complexity consisting of 504 (mainly linear) benchmarks from TPDB



#### $\mathcal{O}(1)$   $\mathcal{O}(n)$   $\mathcal{O}(n^2)$   $\mathcal{O}(n^{>2})$  $\parallel$  **AVIC()**

▶ C\_Complexity consisting of 504 (mainly linear) benchmarks from TPDB



# $O(1)$   $O(n)$   $O(n^2)$   $O(n^{22})$  <  $\infty$  AVG(s)

▶ C\_Complexity consisting of 504 (mainly linear) benchmarks from TPDB



#### $\mathcal{O}(1)$   $\mathcal{O}(n)$   $\mathcal{O}(n^2)$   $\mathcal{O}(n^{>2})$ ) *< ∞* AVG(s)

#### ▶ At most 386 benchmarks might terminate

▶ C Complexity consisting of 504 (mainly linear) benchmarks from TPDB



▶ At most 386 benchmarks might terminate

 $\triangleright$  KoAT2 + TWN + M $\Phi$ RF solves 89% of benchmarks which might terminate

▶ C[on](https://aprove-developers.github.io/KoAT_TWN/)clusion

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- Handle loops with non-linear arithmetic
- Complete for all twn-loops with linear arithmetic

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Thank You!



Analysis of Integer Programs